Model Order Reduction Algorithm for Estimating the Absorption Spectrum

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Supporting Information

ABSTRACT: The ab initio description of the spectral interior of the absorption spectrum poses both a theoretical and computational challenge for modern electronic structure theory. Due to the often spectrally dense character of this domain in the quantum propagator’s eigenspectrum for medium-to-large sized systems, traditional approaches based on the partial diagonalization of the propagator often encounter oscillatory and stagnating convergence. Electronic structure methods which solve the molecular response problem through the solution of spectrally shifted linear systems, such as the complex polarization propagator, offer an alternative approach which is agnostic to the underlying spectral density or domain location. This generality comes at a seemingly high computational cost associated with solving a large linear system for each spectral shift in some discretization of the spectral domain of interest. In this work, we present a novel, adaptive solution to this high computational overhead based on model order reduction techniques via interpolation. Model order reduction reduces the computational complexity of mathematical models and is ubiquitous in the simulation of dynamical systems and control theory. The efficiency and effectiveness of the proposed algorithm in the ab initio prediction of X-ray absorption spectra is demonstrated using a test set of challenging water clusters which are spectrally dense in the neighborhood of the oxygen K-edge. On the basis of a single, user defined tolerance we automatically determine the order of the reduced models and approximate the absorption spectrum up to the given tolerance. We also illustrate that, for the systems studied, the automatically determined model order increases logarithmically with the problem dimension, compared to a linear increase of the number of eigenvalues within the energy window. Furthermore, we observed that the computational cost of the proposed algorithm only scales quadratically with respect to the problem dimension.

1. INTRODUCTION

With recent advances in laser light source technology, X-ray absorption spectroscopy (XAS) has become an important probative tool in chemical physics. The ability of XAS to simultaneously characterize both the electronic and geometrical structure of chemical systems has made it indispensable in the fields of catalysis and photophysics. However, despite the capability of XAS to obtain a wealth of chemically relevant information, the complexity of experimentally obtained XAS spectra often requires a theoretical supplement to obtain a meaningful interpretation of the query phenomenon. Thus, the ability to properly describe the high-energy electronic excitations of molecular systems theoretically is critical in modern electronic structure theory.

In light of its importance in physical chemistry, the prediction of XAS properties poses an interesting challenge for traditional electronic structure methods. This challenge is rooted in the fact that the X-ray region is buried deep within the eigenspectrum of the Hamiltonian and is often spectrally dense. For example, in near edge X-ray absorption fine structure (NEXAFS) spectroscopy, the spectrum consists of many excited states that correspond to excitations of core electrons to diffuse quasibound states. Thus, as system sizes increase, the number of states in the given energy region increases dramatically. Further, it is important to note that because very large basis sets are often required to properly describe the rather diffuse nature of these excited states, the increase in complexity leads to poor scaling with system size.

Many electronic structure methods have been extended to the description of high-energy, X-ray electronic excitations in recent years. In the time domain, real-time density functional theory has been shown to excellently reproduce the X-ray K-edge for molecules within relatively short simulation times. For large systems, however, time domain methods have difficulty taking full advantage of concurrency on modern computing architectures, and are thus not yet a sustainable avenue in routine theoretical inquiry of these phenomena. In contrast, frequency
domain approaches are often favored in these types of calculations as they may be cast as computationally scalable linear algebra problems which are well-suited for massive concurrency. Frequency domain approaches to treat electronic excitations may be separated into two categories which obtain equivalent information: methods which aim to obtain a spectral decomposition of the quantum propagator, i.e., eigenproblem based methods, and methods which solve the response problem directly through the solution of linear systems of equations. Recasting electronic structure methods into eigenproblems has long been the de facto standard frequency domain method for electronically excited states. Through knowledge of the poles (eigenroots) of the quantum propagator, one has direct access to information regarding the electronic excitations (resonances) of the molecular system. In addition, such a spectral decomposition may be used to treat off-resonant perturbations through interpolation schemes known as sum-over-states expressions. Much work has gone into the development of these methods in both wave function theory, such as those based on the coupled-cluster (CC) and algebraic diagrammatic construction (ADC) expansions of the many-body wave function, and self-consistent field theory, such as the linear response time-dependent Hartree–Fock (TD-HF) and density functional theory (TD-DFT). These methods have been shown to accurately predict and reproduce both low and high-energy electronic excitations in molecular systems. Despite their accuracy, however, eigenproblem based methods possess an inherent challenge in the description of high-energy excited states when the eigenroots of interest are buried deep in the eigenspectrum. Traditional methods used to partially diagonalize the propagator, such as the block-Davidson method, are designed to converge to the extreme ends of the eigenspectrum with no built-in mechanism to establish the spectrum’s interior. Several approaches have been described to overcome this problem, including energy specific and restricted energy window methods when the eigenroots of interest are well-separated. Further, in spectrally dense regions of the propagator’s eigenspectrum, iterative diagonalization algorithms require the resolution of many more roots than is often practical to ensure smooth convergence. Methods which solve the response problem through the solutions of linear systems offer an attractive alternative to eigenproblem based approaches in the description of high-energy excitations because they have an intrinsic mechanism to probe the interior of the energy spectrum. In these methods, the probing frequency of the applied perturbation is a chosen parameter. Thus, the interior of the spectrum is easily probed through a number of solutions of linear systems of equations in the desired frequency domain. This simplicity does, however, come at a seemingly significant computational cost compared to eigenproblem based methods. While eigenproblems are able to directly obtain many poles of the eigenspectrum simultaneously, one must solve the linear problem many times over some discretization of the frequency domain to obtain similar results. In general, this discretization must be quite dense to achieve a reasonable accuracy and thus can be more expensive than their eigenproblem based counterparts. Approaches using linear systems and based on the complex polarization propagator (CPP), such as CPP-CC and CPP-SCF, have been shown to be successful in the description of both high-energy and low-energy properties of molecular systems and have been extended to relativistic Hamiltonians as well.

In this work, we introduce a general framework for the prediction of spectrally interior molecular response properties based on model order reduction (MOR) via interpolation. MOR techniques have been successfully applied in different fields of computation science and engineering, where the computational complexity of mathematical models in numerical simulations is reduced. Examples include structural dynamics, sound and vibration analysis, and control theory. The MOR algorithm proposed in this paper aims to overcome the large computational overhead associated with the spectral discretization required by linear system based methods while maintaining the accuracy associated with eigenproblem based methods. Further, the proposed algorithm will be shown to allow for the massively scalable parallelism that is well-suited for modern computing architectures.

2. LINEAR RESPONSE AND ABSORPTION SPECTRUM

In the semiclassical theory of molecular light–matter interaction within the electric dipole approximation, the isotropic absorption cross section for the interaction with plane-polarized light, \( \sigma(\omega) \), at a particular perturbing frequency, \( \omega_p \), is proportional to the trace of the dynamic polarizability tensor, \( \alpha(\omega) \)

\[
\sigma(\omega) \propto \omega \text{Im}(\text{Tr}(\alpha(\omega)))
\]

where \( \eta > 0 \) is a small damping parameter to ensure the convergence of \( \alpha \) in the spectral neighborhoods of resonant perturbations. Within the linear response regime of the first-order polarization propagator approximation (FOPPA), the dynamic polarizability tensor may be written as

\[
\alpha(\omega) = d^T G^{-1}(\omega) d
\]

Here, \( \{d_i | i \in \{x, y, z\} \} \) is the set of dipole operators expressed in the molecular orbital (MO) basis, and \( G(\omega) \) is the first-order polarization propagator. In the following algorithm developments, we restrict the discussion to the FOPPA using a Hartree–Fock reference (TD-HF), although the algorithm presented is completely general to any choice of propagator or reference. Within TD-HF, \( G(\omega) \) may be written as

\[
G(\omega) = H - \omega S
\]

where

\[
H = \begin{bmatrix} A & B \\ B & A \end{bmatrix} \quad S = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}
\]

with \( S = S^T = S^{-1} \) and

\[
A_{ai, bj} = \delta_{ab} (\epsilon_i - \epsilon_j) + (ai|bj)
\]

\[
B_{ai, bj} = (abi|lj)
\]

Here, we have adopted the convention of denoting occupied MOs with indices \( i, j, k, \ldots \) and virtual (unoccupied) MOs with indices \( a, b, c, \ldots \) \( \{\epsilon_i\} \) are taken to be the set of canonical Hartree–Fock MO eigenenergies. The moieties \( (il) \) are the MO basis representation of the antisymmetrized electron-repulsion integrals in Mulliken notation. In this work, we restrict our treatment to the use of strictly real MOs to allow for further simplification of the working expressions. In order to study the spectrum of the pencil \( (H, S) \) let...
\[ \Omega = S^{-1}H = \begin{bmatrix} A & B \\ -B & -A \end{bmatrix} \]

Although the matrix \( \Omega \) is nonsymmetric, it has a number of special properties.\(^{1,6,8,24}\) If \( H \) is positive definite, it may be shown that \( \Omega \) possesses a structured eigendecomposition,\(^{24,85}\) i.e.,

\[
\begin{bmatrix} A & B \\ -B & -A \end{bmatrix} = \begin{bmatrix} U & V \\ V & U \end{bmatrix} \begin{bmatrix} \Lambda & 0 \\ 0 & -\Lambda \end{bmatrix} \begin{bmatrix} U & -V \\ V & U \end{bmatrix}^T
\]

(8)

where \( \Lambda = \text{diag}(\lambda_1, ..., \lambda_n) \) consists of strictly positive eigenvalues, and the eigenvectors are normalized with respect to the metric \( S \)

\[
\begin{bmatrix} U & -V \\ -V & U \end{bmatrix}^T \begin{bmatrix} U & V \\ V & U \end{bmatrix} = I
\]

(9)

As \( H \) is taken to be real in this work, it possesses additional properties that may be exploited in the development of efficient algorithms for estimating the absorption spectrum of the target system. In particular, we may apply the following similarity transformation

\[
T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}
\]

(10)

to \( G(\hat{\omega}) \), yielding

\[
T^T G(\hat{\omega}) T = \begin{bmatrix} K & 0 \\ 0 & M \end{bmatrix} - \hat{\omega}^2 \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}
\]

(11)

where

\[
M \equiv A + B
\]

(12)

\[
K \equiv A - B
\]

(13)

which are, in most cases, positive definite. In this case, the polarizability tensor may be reformulated as

\[
\alpha(\hat{\omega}) = \hat{d} G^{-1}(\hat{\omega}) \hat{d} \quad \hat{d} = [d_x, d_y, d_z]
\]

(14)

where

\[
\hat{G}(\hat{\omega}) = MK - \hat{\omega}^2 I
\]

(15)

Note that the dimension of \( \hat{G}(\hat{\omega}) \) is only half the dimension of \( G(\hat{\omega}) \). Furthermore, it can be shown that

\[
M = (X - Y) \Lambda (X - Y)^T
\]

(16)

\[
K = (X + Y) \Lambda (X + Y)^T
\]

(17)

and

\[
(X - Y)^T (X + Y) = I
\]

(18)

such that the eigenvalues \( \pm \Lambda \) may be computed by

\[
MK = (X - Y) \Lambda^2 (X + Y)^T
\]

(19)

We note that, by making use of \( MK \), the dimension of the eigenvalue problem is also reduced by a factor of 2.\(^{26,57}\)

3. MODEL ORDER REDUCTION OF LINEAR DYNAMICAL SYSTEMS

In this section, we briefly review the theory of model order reduction for linear dynamical systems. The next section will examine its connection to the computation of the absorption spectrum within the FOPPA.

3.1. Linear Dynamical Systems. We consider the linear multiple-input multiple-output (MIMO) system

\[
\Sigma = \begin{bmatrix} (H - sS)x(s) & = & bu(s) \\ y(s) & = & c^T x(s) \end{bmatrix}
\]

(20)

where \( s \) is a derivative or shift operator, \( H \in \mathbb{R}^{n \times n} \) and \( S \in \mathbb{R}^{n \times n} \) are the system matrices, \( b \in \mathbb{R}^{n \times m} \), and \( c \in \mathbb{R}^{m \times n} \). We call \( m \) the dimension (order) of the system \( \Sigma \), \( x \in \mathbb{R}^{n \times m} \) the state vector, \( u \in \mathbb{R} \) the input, and \( y \in \mathbb{R}^{n \times m} \) the output.\(^{52}\) Note that the system \( \Sigma \) is completely characterized by the quadruple \( (H, S, b, c) \).

The transfer function, \( \gamma(s) \), of \( \Sigma \) is defined as

\[
\gamma(s) = c^T (H - sS)^{-1} b
\]

(21)

describes the relation between the input and output of \( \Sigma \), i.e., \( \gamma(s) = \gamma(s)(u(s)) \). For the remainder, we will assume that \( n \gg 1, m \ll n, p \ll n, \) and \( u(s) \equiv 1 \) for all \( s \).

3.2. State Space Transformation. In some cases, it might be more advantageous to describe the system from a point of view different from the original one. In these cases, we may perform a nonsingular state transformation \( T \), i.e., \( \text{det}(T) \neq 0 \), yielding the transformed state

\[
\tilde{x} = T^{-1} x
\]

(22)

describes the relation between the input and output of \( \Sigma \), i.e., \( \gamma(s) = \gamma(s)(u(s)) \). For the remainder, we will assume that \( n \gg 1, m \ll n, p \ll n, \) and \( u(s) \equiv 1 \) for all \( s \).

3.3. Reduced Order Models. The evaluation of the transfer function of a system \( \Sigma \) requires a linear system solve for every value of \( s \). In cases where the system dimension \( n \) is large and a high resolution is required, i.e., a high number of values of \( s \), the evaluation of the transfer function is very expensive. In this work, we examine the effectiveness of model order reduction (MOR) techniques to circumvent this expense. MOR for linear dynamical systems is a technique that approximates a system \( \Sigma \) by another system \( \hat{\Sigma} \) of the same form but of a much lower dimension (order) \( k \ll n \). Consequently, evaluating the transfer function of \( \hat{\Sigma} \) is relatively inexpensive as it only involves linear system solves of dimension \( k \) instead of linear system solves of dimension \( n \) for \( \Sigma \).

Let the system \( \Sigma \) be given by eq \ref{eq:20} and define a nonsingular matrix \( V \in \mathbb{R}^{n \times k} \) with orthonormal columns, i.e., \( V^TV = I \). Then, a reduced order model \( \hat{\Sigma} \) can be constructed by applying a Galerkin projection \( P = VV^T \) onto \( \Sigma \), yielding

\[
\hat{\Sigma} = \begin{bmatrix} (\hat{H} - s\hat{S})\hat{x}(s) & = & \hat{b}u(s) \\ \hat{y}(s) & = & c^T \hat{x}(s) \end{bmatrix}
\]

(23)

where \( \hat{H} = V^THV, \hat{S} = V^TSV, \hat{b} = V^Tb, \) and \( c^T = c^TV \). Note that the length of the state vector \( \hat{x} \) and the dimension of \( \hat{\Sigma} \) are only \( k \ll n \). The purpose of MOR is to construct a \( \hat{\Sigma} \) such that the transfer function of \( \hat{\Sigma} \) approximates very well that of \( \Sigma \)

\[
\gamma_\Sigma(s) \approx \gamma_\hat{\Sigma}(s)
\]

(25)

for all queries \( s \).

3.4. Model Order Reduction via Moment Matching.

One way to construct a matrix \( V \) such that eq \ref{eq:25} holds is by
examining the concepts of moments and moment matching.\(^{52}\) Let the transfer function \(\gamma\) of \(\Sigma\) be given by eq 21. Then the \(\hat{\omega}\)th moment of \(\gamma\) around the point \(s = s_\hat{\omega}\) is defined as the \(\hat{\omega}\)th derivative of \(\gamma\) evaluated at \(s_\hat{\omega}\), i.e.

\[
m_\hat{\omega}(s_\hat{\omega}) = (-1)^{\hat{\omega}} \frac{d^\hat{\omega}}{ds^\hat{\omega}} \gamma(s)|_{s=s_\hat{\omega}}
\]

(26)

for \(\hat{\omega} \geq 0\). Consequently, since \(\gamma(s) = c^T (H - sS)^{-1} b\), the moments at \(s_\hat{\omega}\) are

\[
m_\hat{\omega}(s_\hat{\omega}) = c^T (H - s_\hat{\omega}S)^{-1} (l+1) b \quad l > 0
\]

Note also that the moments determine the coefficients of the Taylor series expansion of the transfer function \(\gamma\) in the neighborhood of \(s_\hat{\omega}\)

\[
\gamma(s) = m_0(s_\hat{\omega}) + m_1(s_\hat{\omega}) \frac{s - s_\hat{\omega}}{1!} + m_2(s_\hat{\omega}) \frac{(s - s_\hat{\omega})^2}{2!} + ...
\]

(27)

Model order reduction via moment matching consists of constructing a subspace \(V \in \mathbb{R}^{n \times km}\) such that the original and reduced order model match moments

\[
m_j(s) = \bar{m}_j(s) \quad j = 1, ..., k
\]

(28)

If all moments to be matched are chosen at zero, i.e., \(s_j = 0\) for \(j = 1, 2, ..., k\), the corresponding model is known as a Padé approximation. In the general case, the problem in eq 28 is known as rational interpolation and can be solved by choosing the projection matrix \(V\) such that

\[
V = \text{span}[(H - s_1S)^{-1} b, (H - s_2S)^{-1} b, ..., (H - s_kS)^{-1} b]
\]

(29)

It can be shown that the matrix \(V\) defined in eq 29 spans a rational Krylov subspace and matches all the zeroth moments at \(s_j\). For more information about the connections between moment matching and rational interpolation, we refer the interested reader to Section 11 of Antoulas’ model order reduction book.\(^{52}\)

4. ESTIMATING ABSORPTION SPECTRUM WITHOUT EXPLICITLY COMPUTING EIGENVALUES AND EIGENVECTORS

The most straightforward way to evaluate the absorption spectrum is to compute eigenvalues and the corresponding eigenvectors of \((H, \hat{S})\). However, as we indicated earlier, when the dimension of \(H\) and \(S\) becomes large (spectrally dense), this approach can be prohibitively expensive (complicated).

It has been shown\(^{30}\) that a special \(K\)-inner product Lanczos algorithm can be used to provide a good approximation to the overall structure of the absorption spectrum without explicitly computing the eigenvalues and eigenvectors of \((H, \hat{S})\). In particular, the Lanczos algorithm can reveal major absorption peaks in the low-frequency region of the spectrum without too many iterations. However, the algorithm gives limited resolution of the absorption spectrum in the spectral interior as the Krylov subspace constructed by the Lanczos iteration contains little spectral information associated with interior eigenvalues of \((H, \hat{S})\).

We now propose an alternative way to evaluate the absorption spectrum without explicitly computing the eigenvalues and eigenvectors of \((H, \hat{S})\). This scheme focuses on approximating the dynamic polarizability tensor \(\alpha(\hat{\omega})\) defined in eq 2 and the absorption spectrum \(\sigma(\omega)\) defined in eq 1 within a specific energy window directly.

First, observe that the dynamic polarizability tensor (eq 2) may be viewed simply as the expectation value of the inverse of \(H - \hat{\omega} \hat{S}\). Hence, the evaluation of \(\alpha(\hat{\omega})\) may be recast into a problem of solving linear equations; i.e., for a specific frequency \(\omega\), we can directly evaluate the absorption spectrum (eq 1) as follows

\[
\sigma(\omega) \propto \omega \text{Im} (\text{Tr}[\hat{d}^T(x(\hat{\omega}))])
\]

(30)

where \(x\) is the solution of the linear system

\[
(H - \hat{\omega} \hat{S})x(\hat{\omega}) = d
\]

(31)

Second, the dynamic polarizability tensor (eq 2) may also be viewed as the transfer function, i.e., the relation between input and output, of the linear dynamical system (see Section 3.1)

\[
\begin{align*}
(H - \hat{\omega} \hat{S})x(\hat{\omega}) &= d \\
\gamma(\omega) &= \hat{d}^T x(\hat{\omega})
\end{align*}
\]

(32)

Consequently, the absorption spectrum can directly be obtained from the output variable \(\gamma\)

\[
\sigma(\omega) \propto \omega \text{Im} (\text{Tr}[\gamma(\omega)])
\]

(33)

In order to evaluate the output \(\gamma\) of system (eq 32) for a given frequency, we again need to solve a linear system of the form in eq 31.

Finally, by exploiting the block structure of \(H\) and performing a state space transformation with eq 10 (see Section 3.2), we obtain an equivalent linear dynamical system for eq 32, but with a halved order

\[
\begin{align*}
(MK - \hat{\omega}^2 I)x(\hat{\omega}) &= \hat{d} \\
\gamma(\omega) &= 2\hat{d}^T Kx(\hat{\omega})
\end{align*}
\]

(34)

such that we obtain the following, compact expressions for the dynamic polarizability tensor

\[
\alpha(\hat{\omega}) = 2\hat{d}^T K(MK - \hat{\omega}^2 I)^{-1} \hat{d}
\]

(35)

and the absorption spectrum

\[
\sigma(\omega) \propto \omega \text{Im} (\text{Tr}[\hat{d}^T K(MK - \hat{\omega}^2 I)^{-1} \hat{d}])
\]

(36)

Note that the dimension of the linear systems to be solved in eq 36 is only half of the dimension of the linear system shown in eq 31.

Clearly, we cannot afford to evaluate \(\sigma(\omega)\) for all \(\omega\)’s of interest. However, this connection to linear dynamical systems allows us to employ MOR techniques (see Section 3.3) to reduce the number of \(\sigma(\omega)\) evaluations in the full dimension. More precisely, we construct a function \(\hat{\sigma}(\omega)\) that approximates \(\sigma(\omega)\) within a specific energy window \([\omega_{\text{min}}, \omega_{\text{max}}]\), but is much cheaper to evaluate. The construction of such an approximate function only requires solving a few linear systems of the form in eq 31 or 34 at a few selected frequencies \(\tau_j, j = 1, 2, ..., k\). The solutions of these linear systems are then used to construct a reduced order model which interpolates the full dynamic polarizability at \(\tau_j\) and provides an approximation to the dynamic polarizability tensor (eq 2) at other frequencies within the predefined energy window. When \(k\) is small, both the construction and the evaluation of the reduced order model are significantly lower than other approaches that are either based
on solving an eigenvalue problem or eq 31 at many different frequencies.

5. INTERPOLATION BASED ALGORITHMS

Let the dimension of matrix $H$ defined in eq 4 be $2n \times 2n$. The dimension of the lower dimensional matrix $\hat{H}$ that we construct for the reduced order model is $3k \times 3k$, where $k \ll n$. One way to construct such a matrix is to first construct a subspace spanned by orthonormal columns of a matrix $V \in \mathbb{R}^{2n \times 3k}$ and then project $H$ onto such a subspace $V$,

$$\hat{H} = V^T HV$$  \hspace{1cm} (37)

If we also let $\hat{S} = V^T SV$ and $\hat{d} = V^T d$, then the absorption spectrum can be approximated by

$$\hat{\sigma}(\omega) \propto \omega \text{Im}(\text{Tr}(\hat{d}^T (\hat{H} - \hat{\omega}\hat{S}))^{-1}\hat{d}))$$ \hspace{1cm} (38)

Clearly, the choice of subspace $V$ is crucial in maintaining the fidelity of the reduced order model. The subspace we use to construct the reduced order model takes the form

$$V = \text{span} [(H - \tau_1 S)^{-1}d, (H - \tau_2 S)^{-1}d, ..., (H - \tau_k S)^{-1}d]$$ \hspace{1cm} (39)

where $\tau_j$, $j = 1, 2, ..., k$ are the interpolation frequencies carefully chosen within the energy window of interest to ensure that

$$\sigma(\omega) \approx \hat{\sigma}(\omega)$$ \hspace{1cm} (40)

for all $\omega$ in the energy window of interest. It follows from the way $V$ is constructed in eq 39 that $\hat{\sigma}$ interpolates $\sigma$ at the interpolation frequencies, i.e.

$$\alpha(\tau_j) = \hat{\alpha}(\tau_j) \hspace{1cm} j = 1, 2, ..., k$$ \hspace{1cm} (41)

Furthermore, since the linear systems eqs 32 and 34 have symmetric system matrices $(H, S)$ and $MK$, respectively, and the input and output matrices $b$ and $c$ are linearly dependent, the Galerkin projection becomes a Petrov–Galerkin projection. \hspace{1cm} (52)

Hence, the original systems eqs 32 and 34 and the corresponding reduced order systems of dimension $k$ match $2k$ moments instead of only $k$ moments in the general case. \hspace{1cm} (52)

In other words, we can obtain the same accuracy for the reduced order models with fewer interpolation frequencies than the general (non-linearly dependent) case.

Algorithm 1 summarizes the construction of the reduced order model and how it is used to obtain an approximation of the absorption spectrum within an energy window of interest. Clearly, the higher the model order $k$ is, the more accurate the approximation is. In the next section, we will show that, even for a relatively small $k$, we can obtain a quite accurate approximation for $\sigma(\omega)$ in an interior spectral window that contains thousands of eigenvalues.

Algorithm 1: Absorption spectrum via model order reduction

```
<table>
<thead>
<tr>
<th>Input</th>
<th>Matrices $H, S, d$, Interpolation frequencies $\tau_1, \tau_2, ..., \tau_k$, Frequencies $\omega_1, \omega_2, ..., \omega_N$, and $\gamma$.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output</td>
<td>Absorption spectrum $\hat{\sigma}(\omega_1), \hat{\sigma}(\omega_2), ..., \hat{\sigma}(\omega_N)$.</td>
</tr>
</tbody>
</table>

for $j = 1, 2, ..., k$ do

1. Linear system solve $x_j = (H - \tau_j S)^{-1}d$.

end

2. QR factorization $X = VR$.

3. Construct $\hat{H} = V^T HV$, $\hat{S} = V^T SV$, and $\hat{d} = V^T d$.

for $j = 1, 2, ..., N$ do

4. Compute $\hat{\sigma}(\omega_j) = \omega_j \text{Im}(\text{Tr}(\hat{d}^T (\hat{H} - (\omega_j + i\gamma)\hat{S}))^{-1}\hat{d}))$.

end
```

Although algorithm 1 provides a general framework for constructing a reduced order model for estimating the absorption spectrum defined by $(H, S)$, it is more efficient to exploit the structure of $(H, S)$ and construct a reduced order model for eq 34 instead. Such a reduced order model may be obtained by projecting eq 34 onto a subspace defined by

$$\tilde{V} = \text{span} [(MK - \tau_1^2 I)^{-1}\hat{d}, (MK - \tau_2^2 I)^{-1}\hat{d}, ..., (MK - \tau_k^2 I)^{-1}\hat{d}]$$ \hspace{1cm} (42)

where $\tau_j$, $j = 1, 2, ..., k$ are again the interpolation frequencies. Because the matrix $MK$ is self-adjoint with respect to the $K$-inner product, it is more convenient to carry out the projection using the $K$-inner product and projecting $MK$ onto a subspace spanned by a $K$-orthonormal basis; i.e., $\tilde{V}^T K\tilde{V} = I$ is satisfied. If we let

$$MK = \tilde{V}^T KMK$$ \hspace{1cm} (43)
then the approximation to the absorption spectrum provided by the structure exploiting reduced order model can be expressed by

$$\tilde{\hat{d}} = \hat{V}^T \hat{K} \hat{d}$$  \hspace{1cm} (44)$$

By exploiting the block structure of $H$, we can prove that eqs 38 and 45 are equivalent. However, the latter is cheaper to construct, both in terms of the number of floating point operations and memory usage, since it only involves matrices of size $n \times n$ and vectors of size $n$. The structure exploiting the model order reduction algorithm for approximating the absorption spectrum is outlined in algorithm 2.

Algorithm 2: Absorption spectrum via structure exploiting model order reduction

Input: Matrices $M, K, \hat{d}$
Interpolation frequencies $\tau_1, \tau_2, \ldots, \tau_k$
Frequencies $\omega_1, \omega_2, \ldots, \omega_N$, and $\eta$.

Output: Absorption spectrum $\hat{\sigma}(\omega_1), \hat{\sigma}(\omega_2), \ldots, \hat{\sigma}(\omega_N)$.

for $j = 1, 2, \ldots, k$ do
    Linear system solve $\hat{x}_j = (M\hat{K} - \tau_j I)^{-1} \hat{d}$.
end

QR factorization $X = \hat{V}\hat{R}$, with $\hat{V}^T \hat{K} \hat{V} = I$.

Construct $M\hat{K} = \hat{V}^T \hat{K} \hat{M} \hat{K} \hat{V}$ and $\hat{d} = \hat{V}^T \hat{d}$.

for $j = 1, 2, \ldots, N$ do
    Compute $\hat{\sigma}(\omega_j) = \omega \text{Im} \left( \text{Tr} \left[ \hat{d}^T (M\hat{K} - (\omega_j + i\eta)^2 I)^{-1} \hat{d} \right] \right)$.
end

Note that both algorithms 1 and 2 require a choice of the interpolation frequencies $\tau_j$. The number of these interpolation frequencies and their locations solely determine the quality of the absorption spectrum approximations. The simplest way to choose these interpolation frequencies is to partition the energy window of interest evenly by a uniform interpolation grid. However, because the absorption spectrum can be highly oscillatory in certain regions within the energy window, a very fine grid may be needed to resolve the high oscillation. As a result, the number of the reduced order model, which is proportional to the number of interpolation frequencies, can be exceedingly high.

A more effective strategy for choosing the interpolation frequencies is to choose these frequencies in an adaptive fashion. We now propose a refinement strategy, which is graphically illustrated in Figure 1. To start this procedure, we choose in the first level a coarse, uniform grid of interpolation frequencies (marked by black square) to construct the level-1 reduced order model. The set of interpolation frequencies is refined by adding the midpoints (marked by black triangle) between two adjacent level-1 interpolation frequencies. This enlarged set forms the second level of interpolation frequencies, yielding a more accurate level-2 reduced order model. Next, we choose the midpoints between two adjacent level-2 interpolation frequencies as candidates (marked by open circle) to enlarge the set in the third level. We also estimate the approximation error by computing the relative difference between the level-1 and level-2 reduced order models for the entire energy window. If the error estimate at an interval between two adjacent level-2 interpolation frequencies is above a prescribed error tolerance, the midpoint (marked by black circle) is added to the existing set of interpolation frequencies. The enlarged set results in an even more accurate level-3 reduced order model. This refinement process continues until the error estimate at the entire energy window is below the threshold or when the refined model order exceeds a prescribed upper bound.

6. COMPUTATIONAL RESULTS

The proposed automatic MOR algorithm has been implemented in the Chronus Quantum software package59 and in MATLAB (https://bitbucket.org/roelvb/mor4absspectrum). The following numerical experiments were performed using a single Sandy–Bridge Intel Xeon compute node (E5-2650v2@2.60 GHz) with 16 cores and 512 GB DDR3 RAM. All of the water cluster test cases were performed using the 6-31G(d) basis set without the use of molecular symmetry and were chosen for their dense spectral character in the X-ray spectral domain. All of the geometries for the water clusters used in this work may be found in the Supporting Information.

The implementation of the MOR utilizes a synchronized approach to the Generalized Minimum Residual (GMRES)60 algorithm for the solution of the linear systems. In this approach, each linear system is solved individually via the standard GMRES algorithm, but its matrix-vector products (GEMVs), which constitute the dominant cost, are synchronized and performed in batches. Hence, the GEMVs become matrix–matrix products (GEMMs) and allow for optimal efficiency and cache utilization through the use of level 3 BLAS operations. In all experiments we used a block size of 12, coming from combining the 3 dipole vectors at 4 interpolation frequencies.

Several numerical experiments were performed to demonstrate the performance and accuracy of the proposed MOR algorithms. Since the interpolation points are merely used to construct a reduced order model, it is conceivable that we may choose them to be real numbers instead of complex numbers that contain a small imaginary damping factor. The advantage of choosing real interpolation points is that all linear systems can be solved in real arithmetic. However, as we will see below, this approach may not lead to any performance gain and can even lead to a performance degradation.

We also examined how the order of the reduced order model changes as the damping factor $\eta$ changes and as the size of the molecular system increases as well as the overall computational scaling of the proposed method using the aforementioned water clusters. Numerical comparisons are made to the Lorentzian broadened poles of the propagator using the oscillator strengths.62–64 The eigenvalues and oscillator strengths were computed via BSEPAC65,66 on a Cray XC40 with Haswell Intel Xeon compute nodes (E5-2698v3@2.3 GHz, 2 × 16 cores, 128 GB DDR4 RAM). The broadening factor was set equal to $\eta$ for comparison with the approximate MOR experiments.

6.1. Real versus Complex Interpolation Frequencies.

We start with a cluster of 5 water molecules and are interested in computing the absorption spectrum in the energy window $[540 \text{ eV}, 600 \text{ eV}]$. The dimension of the matrix $H$ (eq 4) was 2n = 6500, and $H$ had 394 eigenvalues in the energy window. The damping factor was $\eta = 1 \text{ eV}$, and the tolerance for solving the linear systems was set to $10^{-6}$. The damping factor was chosen to roughly mimic the effects of the core-hole lifetime of the K-edge transitions in oxygen and vibrational broadening.65 It is important to note that the broadening due to the damping parameter in these simulations is purely phenomenological, as no vibronic effects are being explicitly treated.

In the first experiment, we used a fixed order $k = 32$ for the reduced order models and only changed the interpolation
frequencies $\tau_j, j = 1, 2, \ldots, k$. We computed the absorption spectrum by algorithms 1 and 2 for both real $\tau_j = \omega_j$ and complex $\tau_j = \omega_j + i\eta_j$, where $\omega_j$ values were uniformly selected in the energy window. The corresponding results are presented in Figure 2 and in the top part of Table 1. Note that, by using complex interpolation frequencies $\tau_j$, we obtained good approximations of the absorption spectrum from both algorithms 1 and 2 even with such a small model size. On the other hand, the use of real $\tau_j$ resulted in poor approximations for both algorithms. This is due to the fact that the (real) interpolation frequencies are often very close to the (real) eigenvalues of $(H, S)$ or $MK$, resulting in ill-conditioned linear systems being solved. However, this can be avoided with complex interpolation frequencies.

Next, we repeated the previous experiment but chose the interpolation frequencies via the adaptive refinement strategy introduced in Section 5. As the error estimates, we used the difference of the normalized absorption spectrum between two consecutive refinement levels. The tolerance was set to 0.01, which corresponds to a 1% change in the overall absorption spectrum on the window [540 eV, 600 eV]. This resulted in reduced order models of different orders $k$, reported in the middle part of Table 1. We observe that, in terms of the order $k$, the use of complex interpolation frequencies has a significant advantage over the use of real frequencies. Further, we also observe that the adaptive refinement strategy for algorithms 1 and 2 resulted in very similar orders $k$ when the same types of interpolation frequencies are used.

The corresponding computational expense for the previous two experiments is reported in Table 1 using various metrics. We observe that, for both fixed and adaptive model orders, the computational cost required for algorithm 2 was significantly lower than that of algorithm 1. This is expected as both methods are mathematically equivalent and the former only deals with linear systems of half the dimension of the latter. Furthermore,
Table 1. Effect of Using Real and Complex Interpolation Frequencies \(\tau\) on the MOR Evaluation of XAS Spectra for 5 \(\text{H}_2\text{O}\) Clusters\(^a\)

<table>
<thead>
<tr>
<th>algorithm</th>
<th>(k)</th>
<th>GEMMs</th>
<th>wall (s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>algorithm 1: real (\tau)</td>
<td>32</td>
<td>1052</td>
<td>19.76</td>
</tr>
<tr>
<td>algorithm 1: complex (\tau)</td>
<td>32</td>
<td>776</td>
<td>40.97</td>
</tr>
<tr>
<td>algorithm 2: real (\tau)</td>
<td>32</td>
<td>985</td>
<td>9.78</td>
</tr>
<tr>
<td>algorithm 2: complex (\tau)</td>
<td>32</td>
<td>646</td>
<td>17.50</td>
</tr>
<tr>
<td>algorithm 1: real (\tau)</td>
<td>218</td>
<td>7440</td>
<td>137.01</td>
</tr>
<tr>
<td>algorithm 1: complex (\tau)</td>
<td>87</td>
<td>2285</td>
<td>115.50</td>
</tr>
<tr>
<td>algorithm 2: real (\tau)</td>
<td>211</td>
<td>6541</td>
<td>65.31</td>
</tr>
<tr>
<td>algorithm 2: complex (\tau)</td>
<td>87</td>
<td>2026</td>
<td>52.70</td>
</tr>
<tr>
<td>conventional CPP (1000 points)</td>
<td>18 126</td>
<td>538.90</td>
<td></td>
</tr>
</tbody>
</table>

\(^a\)Computational expense for algorithms 1 and 2. Here \(k\) is the reduced order. GEMMs is the total number of matrix–matrix products, and the total wall-clock time is given in seconds.

Although real interpolation frequencies allow us to solve only real linear systems, we observe that, in the case of adaptively chosen model orders, the drastic decrease in model order required for complex interpolation frequencies over real frequencies offsets this advantage. Finally, we note at the bottom of Table 1 that the use of algorithm 2 with complex interpolation frequencies reduces the computational expense by a factor of almost 10 compared to conventional complex polarization propagator calculations on a fine grid.

6.2. Computational Scaling. We now consider water clusters consisting of 5, 10, 15, 20, and 25 water molecules. The corresponding matrix dimensions are shown in Table 2. The energy window \([540 \text{ eV}, 600 \text{ eV}]\) and damping factor \(\eta = 1 \text{ eV}\) were the same as for the previous experiments. We computed the absorption spectrum via algorithm 2 with complex interpolation frequencies chosen adaptively. The obtained absorption spectra are shown in Figure 3.

The MOR results are given in Table 2, where we present the orders \(k\) of the reduced order models, the total number of GEMMs, and the total wall-clock time for different GMRES convergence tolerances. First, we observe that the order \(k\) of the reduced order models increases sublinearly with the number of waters, whereas the number of eigenvalues inside the energy window \(\#\lambda\) grows linearly with respect to the problem dimension. Second, the order \(k\) decreases for increasing GMRES convergence tolerances. This is due to the fact that if we solve the linear systems less accurately, we match the moments less accurately and hence we need more interpolation points (a higher value of \(k\)) for the same accuracy of the reduced order model and the corresponding absorption spectra. Moreover, the order \(k\) seems to stagnate around GMRES tolerance \(10^{-5}\) and there were no visual differences any more between the obtained absorption spectra for GMRES tolerances \(10^{-5}\) and \(10^{-6}\).

The total wall-clock time and number of GEMMs are also shown in Figure 4. The left figure illustrates that the wall-clock time scales quadratically with respect to the problem dimension, compared to a cubic scaling for a full diagonalization. Moreover, the right figure shows that the number of GEMMs only scales logarithmically, compared to an expected linear scaling for iterative eigensolvers since the number of eigenvalues inside the energy window grows linearly. It is worth noting that the vector space dimension of the linear problem also scales quadratically with system size.

6.3. Effect of Damping Factor. We examine the effect of the damping factor on the overall effectiveness of the proposed MOR algorithm in the low damping limit. We revisit the case of water clusters containing 5 water molecules from the previous subsections over the same energy window. Specifically, we examine the effect on the damping parameter \(\eta \in [0.1, 1] \text{ eV}\) on the model order required to achieve a convergence of 1% in the absorption spectrum. The MOR results were obtained via algorithm 2 using adaptively chosen complex interpolation frequencies. The resulting spectra are presented in Figure 5a–c.

The effect of the damping factor on the automatically selected model order is illustrated in Figure 5d. In this figure, we observe that by decreasing the damping factor the reduced model order \(k\) first remains almost constant until \(0.5 \text{ eV}\) and then starts to slightly increase for smaller values of \(\eta\). Even in the low damping limit (0.1 eV), when the obtained absorption spectrum is exceptionally complicated and oscillatory relative to the previous experiments (1 eV), the required model order is still well within the realm of practicality for routine calculations. Thus, the proposed MOR algorithm may be used as a general procedure which requires no assumption of (the smoothness of) the underlying absorption spectrum.

7. CONCLUSION

In this work, we have presented a novel, adaptive algorithm for the \textit{ab initio} prediction of the absorption spectrum based on model order reduction techniques applied to the quantum propagator. While this approach is general to any spectral domain, the power of the proposed method is in those spectral domains which are dense and interior in the propagator’s eigenspectrum. The accuracy and efficiency of this method to predict the X-ray absorption spectrum have been demonstrated.

Table 2. Numerical Experiments for the Evaluation of the XAS Spectrum of Variously Sized \(\text{H}_2\text{O}\) Clusters via Algorithm 2 with Adaptively Chosen Complex Interpolation Frequencies\(^a\)

| waters | GMRES tol = \(10^{-4}\) | GMRES tol = \(10^{-5}\) | GMRES tol = \(10^{-6}\) |
|--------|---------|---------|---------|---------|---------|---------|
| \# \(n\) \#\(\lambda\) | \(k\) | GEMMs | wall (s) | \(k\) | GEMMs | wall (s) | \(k\) | GEMMs | wall (s) |
| 5 | 3250 | 394 | 76 | 968 | 27.2 | 87 | 1654 | 43.4 | 87 | 2025 | 52.7 |
| 10 | 13 000 | 1456 | 99 | 1749 | 636.2 | 83 | 2404 | 867.1 | 82 | 3235 | 1157.0 |
| 15 | 29 250 | 3183 | 99 | 2221 | 4141.8 | 82 | 2946 | 5511.9 | 82 | 4018 | 7534.4 |
| 20 | 52 000 | 5524 | 123 | 2742 | 14 665.8 | 89 | 3317 | 17 807.0 | 91 | 4594 | 25 656.5 |
| 25 | 81 250 | 8530 | 123 | 2610 | 34 128.8 | 95 | 3694 | 47 697.1 | 94 | 5020 | 65 284.1 |

\(^a\)Here, MK is of dimension \(n\) with \#\(\lambda\) eigenvalues lying within the energy window \([540 \text{ eV}, 600 \text{ eV}]\). The comparisons are made for GMRES convergence tolerances of \(10^{-4}\), \(10^{-5}\), and \(10^{-6}\), with \(k\) as the reduced model order, GEMMs as the total number of matrix–matrix products, and the total wall-clock time given in seconds.
using a series of water clusters. Water clusters were chosen as an especially challenging case study as the propagator is spectrally dense in the spectral neighborhood of the water’s oxygen K-edge. The numerical experiments have shown that complex interpolation frequencies should be preferred over real ones and that in this case the order of the reduced order models only slightly increased with the problem dimension, in contrast to the rapid growth of the number of eigenvalues inside the energy window. Moreover, the wall-clock time for the proposed model order reduction algorithm scales only quadratically with respect to the dimension of the problem, compared to cubic scaling for eigenvalue based algorithms. Further, it was shown that, even in the limit of highly oscillatory and low damping absorption spectra, the proposed algorithm remains practical and thus may be treated as agnostic to the underlying nature of the spectrum. While results were presented only for the TD-HF method, the proposed adaptive MOR algorithm is general to any choice reference, propagator, or perturbation. Further, although it is not expressly considered in this work, this technique is well-suited for parallelism on a massive scale as each of the linear system solutions is completely independent from the other, thus allowing for minimal communication. With the proposed MOR algorithm, routine study of X-ray absorption spectra for medium-to-large sized systems is simplified.

**ASSOCIATED CONTENT**

**Supporting Information**
The Supporting Information is available free of charge on the ACS Publications website at DOI: 10.1021/acs.jctc.7b00402.

Tables of Cartesian coordinates (PDF)

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**Figure 3.** Numerical experiments for the evaluation of the XAS spectrum of variably sized H₂O clusters via algorithm 2 with adaptively chosen complex interpolation frequencies. The MOR results are compared to the Lorentzian broadened poles of the propagator, labeled eigensystem. A damping parameter of 1 eV was chosen both for the MOR calculations and the broadening factor of the Lorentzians for the reference.
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Figure 4. Cluster of H2O molecules: MOR results for the absorption spectra computed via algorithm 2 with adaptively chosen complex interpolation frequencies. The comparisons are made for GMRES convergence tolerances of 10−4, 10−5, and 10−6.

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Figure 5. Numerical experiments for the evaluation of the XAS spectrum of 5 H₂O clusters by algorithm 2 using different damping factors η. (a–c) The MOR results are compared to the Lorentzian broadened poles of the propagator, labeled eigensystem. (d) Effect of the damping factor η on the reduced model order k.


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